



How to use CAN interface

In Factory_Init:

```
CAN_init();
```

In Factory_build:

```
ECAN_SetRXBnInterruptHandler(CAN_newMsg);  
CAN_onReceiveCan(&receiveCan);  
CAN_setSender(idSender);
```

In Factory_start:

```
CAN_startBehaviour();
```

Somewhere for process input can message:

```
void receiveCan(uint8_t idSender, uint8_t idMsg, uint32_t canData) {  
    .....  
}
```

For send can message:

```
CAN_sendCanMsg(uint8_t idRecipient, uint8_t idMsg, uint32_t data);
```